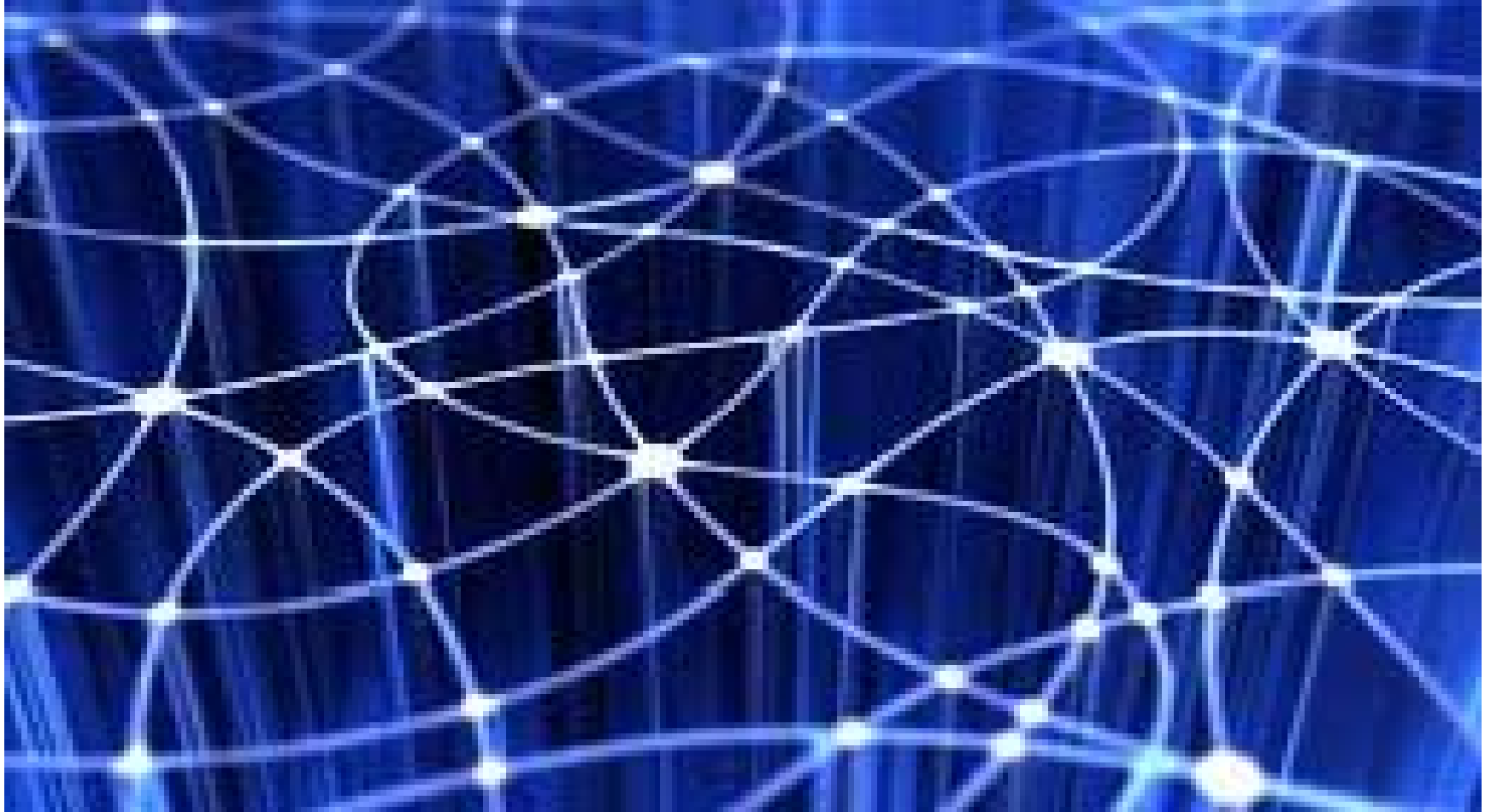


# Solving Reaction Networks



# General reaction network

A set of  $n$  isotopes with abundances  $Y_i$ ,

Consider 1- and 2-body rates only, these rates can produce or destroy each isotope

$$\frac{dY_i}{dt} = \left[ \sum_{j,k} Y_j Y_k \rho N_A \langle \sigma v \rangle_{jk \rightarrow i} + \sum_l \lambda_{l \rightarrow i} Y_l \right] \quad \text{production}$$

$$- \left[ \sum_m Y_i Y_m \rho N_A \langle \sigma v \rangle_{im \rightarrow \text{any}} + \sum_n \lambda_{i \rightarrow n} Y_i \right] \quad \text{destruction}$$

Note that this depends on mass density  $\rho$  and temperature (through  $\langle \sigma v \rangle$  and  $\lambda$ ) so this requires input from a stellar model.

Needs to be solved numerically. This is not trivial as system is very stiff (reaction rate timescales vary by many many orders of magnitude)

# Solving reaction networks numerically

## General problem:

Vector of abundances at time  $t$   $Y_i(t)$

Set of differential equations (the reaction network)  $\frac{dY_i}{dt} = f(\vec{Y})$

Want to calculate  $Y_i(t + \Delta t)$  from  $Y_i(t)$  so need  $\Delta Y_i = Y_i(t + \Delta t) - Y_i(t)$

## Simplest explicit approach:

$$\Delta Y_i = f(\vec{Y}(t)) \Delta t$$

Problem: as system is very stiff (rates vary by many orders of magnitude) this requires extremely small time steps, and so at least in its simplest form this is not practical

# Solving reaction networks numerically

Simplest implicit approach:

$$\Delta Y_i = f(\vec{Y}(t + \Delta t)) \Delta t \quad (1)$$

To first order:

$$f_i(\vec{Y}(t + \Delta t)) = f_i(\vec{Y}(t)) + \sum_j \boxed{\frac{\partial f_i(\vec{Y}(t))}{\partial Y_j}} \Delta Y_j + \dots$$

**Jacobian  $J_{ij}$**

Insert into (1):

$$\frac{\Delta Y_i}{\Delta t} = f_i(\vec{Y}(t)) + \sum_j J_{ij} \Delta Y_j$$

# Solving reaction networks numerically

Or in vector/matrix notation:

$$\frac{\Delta \vec{Y}}{\Delta t} = \vec{f}(t) + \tilde{J} \Delta \vec{Y}$$

Solve for  $\Delta Y$ :

$$\frac{\Delta \vec{Y}}{\Delta t} - \tilde{J} \Delta \vec{Y} = \vec{f}(t) \quad \rightarrow \quad \Delta \vec{Y} \left( \frac{\tilde{1}}{\Delta t} - \tilde{J} \right) = \vec{f}(t)$$

$$\rightarrow \Delta \vec{Y} = \vec{f}(t) \left( \frac{\tilde{1}}{\Delta t} - \tilde{J} \right)^{-1}$$

Main numerical task:  
Setup this matrix and invert it